

UNIVERSITY OF FORT HARE

ADVANCED NUMERICAL DIFFERENTIATION AND INTEGRATION

MAQ 522

NOVEMBER EXAMINATIONS

Time: 3 hours

Subject: Applied Mathematics

Marks: 180

**This paper consists of four pages
including the cover page.**

Examiner: **Dr. S. J. Childs**

External examiner: **Prof. G. Lubczonok**

INSTRUCTIONS

All questions may be answered.

Show your working.

Sloppy work will be penalised.

1. (a) Derive the second order Runge-Kutta method. (20 marks)

- (b) Use the version that is the modified Euler's method to obtain $f(0.05)$, by solving

$$\frac{df}{dx} = 3e^{2x}, \text{ with an initial value of } f(0) = \frac{1}{5} \text{ and a step length of}$$

$$h = 0.05. \quad (12 \text{ marks})$$

2. Suppose that

$$w_{i+1} = w_i + h\phi(t_i, w_i, h), \quad w_0 = \alpha$$

and

$$\tilde{w}_{i+1} = \tilde{w}_i + h\tilde{\phi}(t_i, \tilde{w}_i, h), \quad \tilde{w}_0 = \alpha$$

are general methods for solving an I.V.P., that the first has an $O(h^n)$ local truncation error in ϕ and that the second has an $O(h^{n+1})$ local truncation error in $\tilde{\phi}$, then:

- (a) Show that $\tau_{i+1} \approx \frac{1}{h} (\tilde{w}_{i+1} - w_{i+1})$ to first order. (22 marks)

- (b) Formulate $\tau_{i+1}(qh)$ in terms of $\tau_{i+1}(h)$, the original, $O(h^n)$ local truncation error

$$(q > 0). \quad (5 \text{ marks})$$

- (c) Re-write this $\tau_{i+1}(qh)$ in terms of $(\tilde{w}_{i+1} - w_{i+1})$. (1 mark)

- (d) If one sets a tolerance, ϵ , on this value, then $|\tau_{i+1}| \leq \epsilon$. Formulate an expression for

$$\text{the } q \text{ that this tolerance dictates.} \quad (8 \text{ marks})$$

3. Based on your answer to the previous question, outline the steps you would implement

in a Runge-Kutta-Fehlberg, RKF4-5 algorithm which implements

$$w_{i+1} = w_i + \frac{25}{216}k_1 + \frac{1408}{2565}k_3 + \frac{2197}{4104}k_4 - \frac{1}{5}k_5$$

and

$$\tilde{w}_{i+1} = \tilde{w}_i + \frac{16}{135}k_1 + \frac{6656}{12825}k_3 + \frac{28561}{56430}k_4 - \frac{9}{50}k_5 + \frac{2}{55}k_6,$$

in which

$$\begin{aligned} k_1 &= hf(t_i, w_i) \\ k_2 &= hf\left(t_i + \frac{1}{4}h, w_i + \frac{k_1}{4}\right) \\ k_3 &= hf\left(t_i + \frac{3}{8}h, w_i + \frac{3}{32}k_1 + \frac{9}{32}k_2\right) \\ k_4 &= hf\left(t_i + \frac{12}{13}h, w_i + \frac{1932}{2197}k_1 - \frac{7200}{2197}k_2 + \frac{7296}{2197}k_3\right) \\ k_5 &= hf\left(t_{i+1}, w_i + \frac{439}{216}k_1 - 8k_2 + \frac{3680}{513}k_3 - \frac{845}{4104}k_4\right) \\ k_6 &= hf\left(t_i + \frac{1}{2}h, w_i - \frac{8}{27}k_1 + 2k_2 - \frac{3544}{2363}k_3 + \frac{1859}{4104}k_4 - \frac{11}{40}k_5\right). \end{aligned}$$

(25 marks)

4. The exact formula for the Adams-Bashforth, four-step, $O(h^4)$ -accurate method is

$$\begin{aligned} y(t_{i+1}) &= y(t_i) + \frac{h}{24} [55f(t_i, w_i) - 59f(t_{i-1}, w_{i-1}) + 37f(t_{i-2}, w_{i-2}) \\ &\quad - 9f(t_{i-3}, w_{i-3})] + \frac{251}{720}h^5 f^5(\xi_{i+1}), \end{aligned}$$

for $t_{i-3} < \xi_{i+1} < t_{i+1}$. The exact formula for the Adams-Moulton, three-step, $O(h^4)$ -accurate method is

$$y(t_{i+1}) = y(t_i) + \frac{h}{24} [9f(t_{i+1}, w_{i+1}) + 19f(t_i, w_i) - 5f(t_{i-1}, w_{i-1}) + f(t_{i-2}, w_{i-2})] - \frac{19}{720} h^5 f^5(\bar{\xi}_{i+1}),$$

for $t_{i-2} < \tilde{\xi}_{i+1} < t_{i+1}$. These two multistep methods are suitably matched for use in a predictor-corrector algorithm. Since predictor-corrector methods give rise to two estimates at each step, they lend themselves naturally to an error control procedure.

- (a) Formulate the error, at each step in the algorithm, in terms of the difference between the solutions of the predictor stage, $w_{i+1}^{(0)}$, and the corrector stage, $w_{i+1}^{(1)}$, as well as the step size, h . (39 marks)
- (b) Show that setting a tolerance, ϵ , on this error enables one to formulate an expression for a scaling factor, q , with which to vary the step size, h . (19 marks)
5. Based on the information in the previous question, outline the steps you would implement in an Adams, $O(h^4)$ -accurate, variable-step-size, predictor-corrector algorithm. (31 marks)